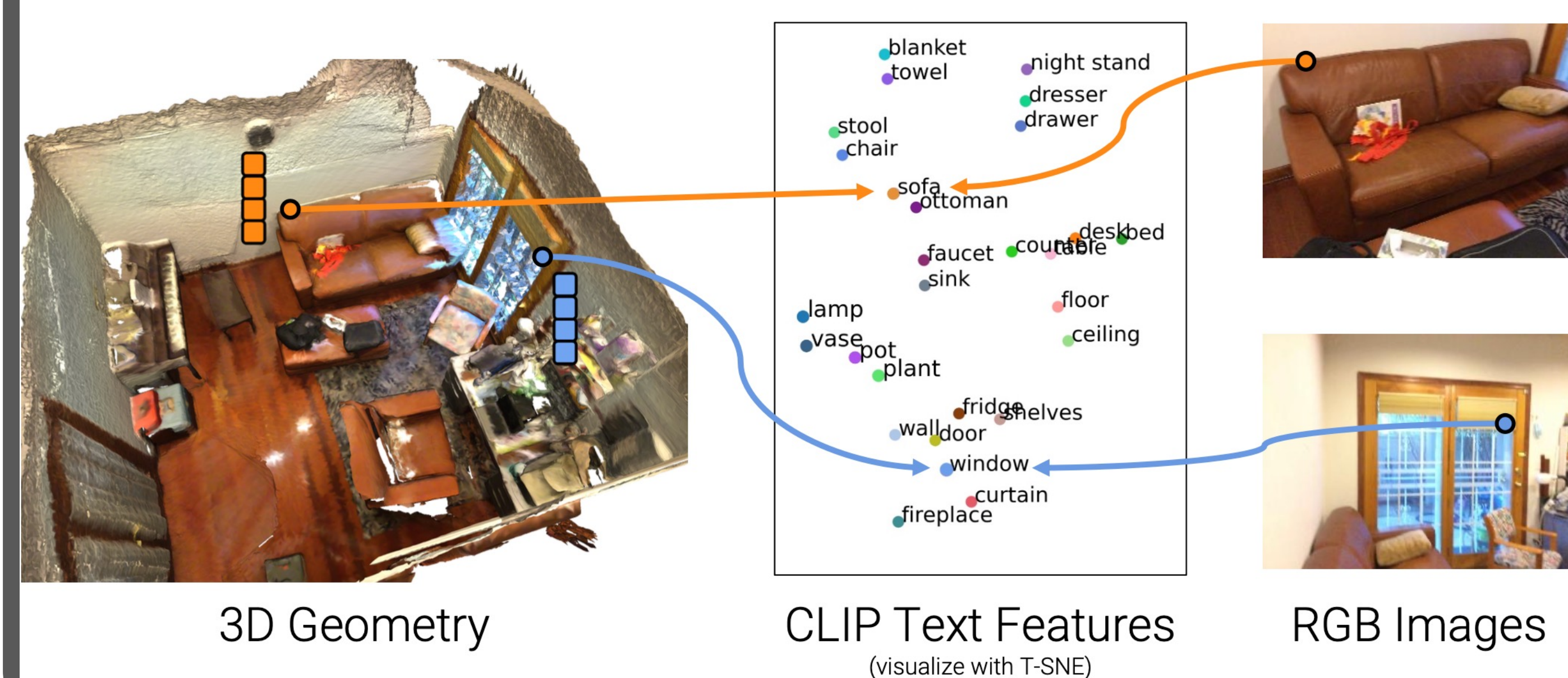


1. Introduction

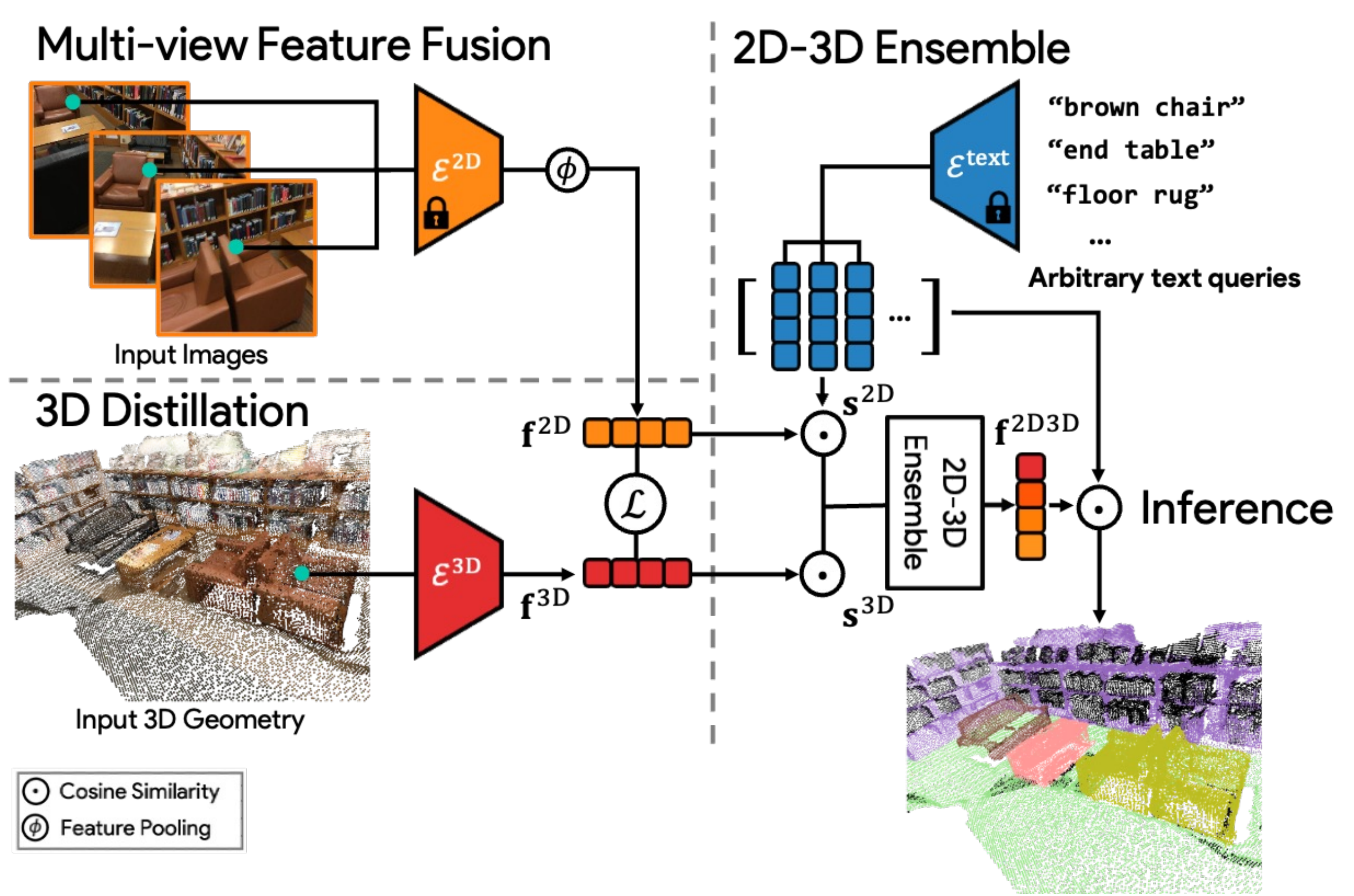
Problem: Traditional 3D scene understanding only train and test on some fixed common classes

Goal: A zero-shot approach to perform novel 3D scene understanding tasks with arbitrary queries

Our Key Idea: Co-embed 3D features with CLIP text and image features

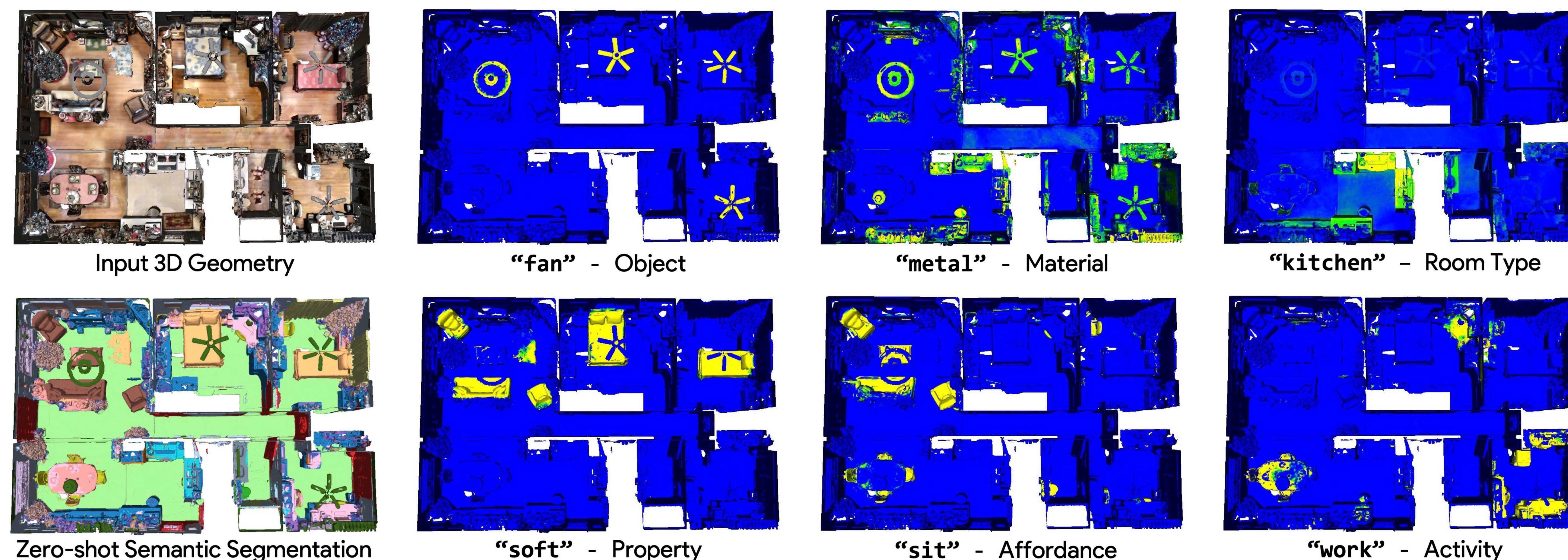


2. Method



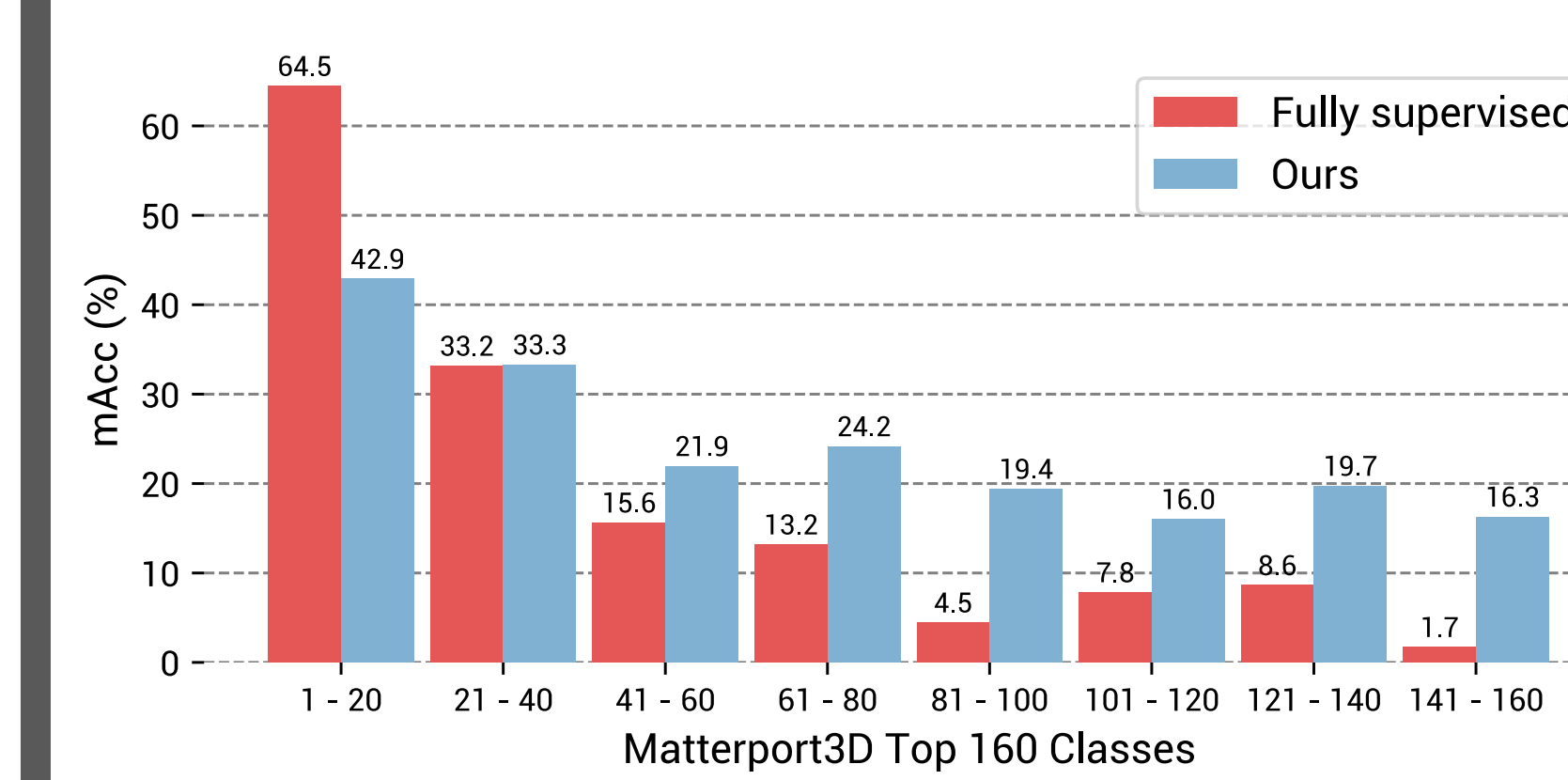
Paper, code, and real-time demo are available: pengsongyou.github.io/openscene

3. Zero-shot Open-vocabulary Scene Exploration



5. More Studies

Robust to Finding Rare Object

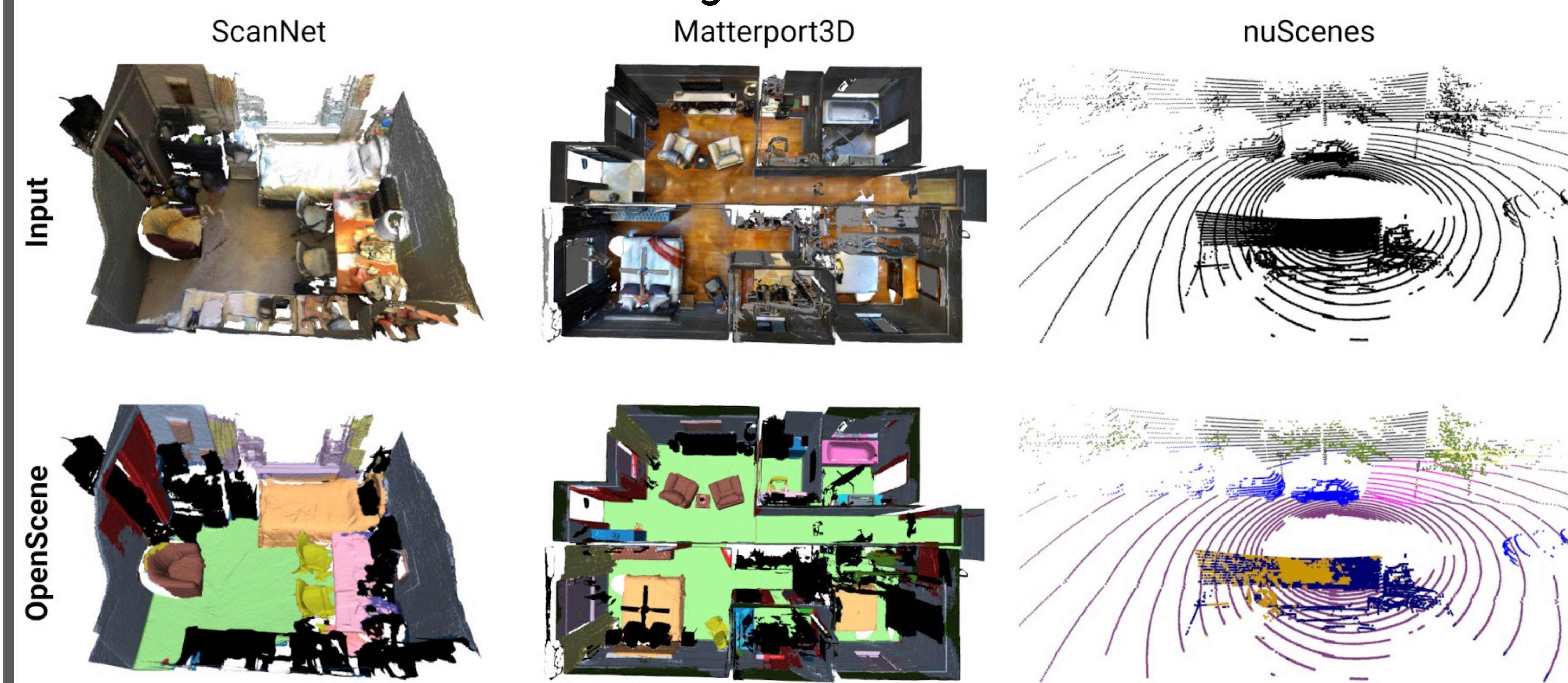


Ablation Study

		ScanNet [11]		Matterport3D [4]	
		mIoU	mAcc	mIoU	mAcc
Ours	2D Fusion	50.0	62.7	32.3	40.0
	3D Distill	52.9	63.2	41.9	51.2
LSeg	2D-3D Ens.	54.2	66.6	43.4	53.5
	Ours	41.4	63.6	32.4	45.0
OpenSeg	3D Distill	46.0	66.3	41.3	55.1
	2D-3D Ens.	47.5	70.7	42.6	59.2

4. Additional Applications

3D Semantic Segmentation Benchmarks



Object Retrieval

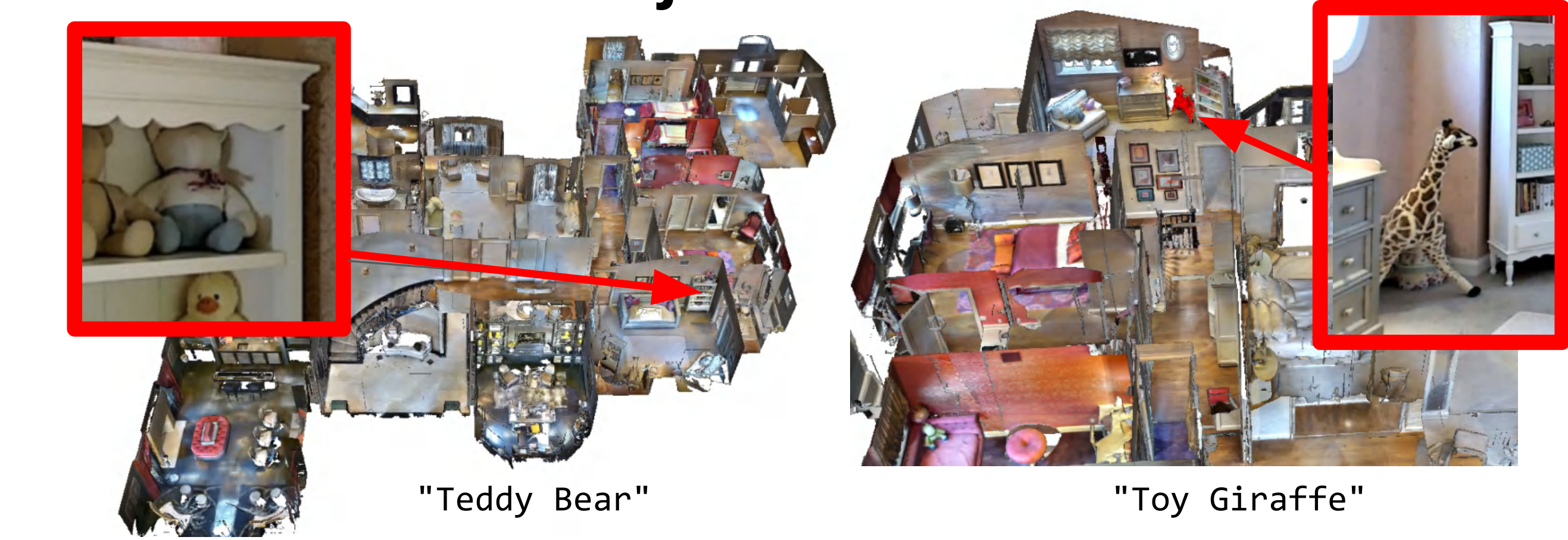


Image-based 3D Object Detection

